

## Chapter 4 Classification of Planar Linear Systems

$$\begin{aligned}x' &= ax + by \\y' &= cx + dy\end{aligned}$$

Matrix form:

$$X' = AX \\ X = \begin{pmatrix} x \\ y \end{pmatrix}, A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

The characteristic polynomial for eigenvalues is

$$\begin{aligned}\det(A - \lambda I) &= 0 \\ \lambda^2 - (a + b)\lambda + ad - bc &= 0\end{aligned}$$

- Trace:  $T = \text{Tr}(A) = a + b$
- Determinant:  $D = \det(A) = ad - bc$
- The characteristic equation is

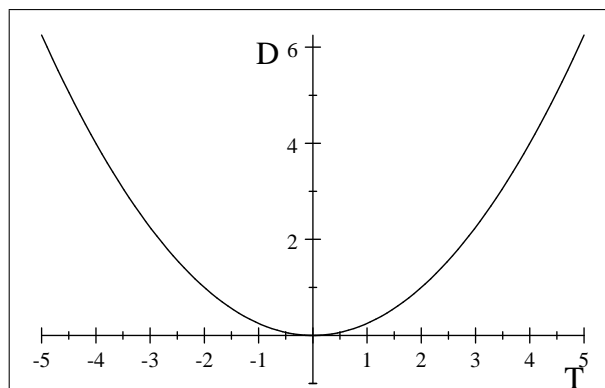
$$\lambda^2 - T\lambda + D = 0$$

- Eigenvalues

$$\lambda_1 = \frac{T - \sqrt{T^2 - 4D}}{2}, \quad \lambda_2 = \frac{T + \sqrt{T^2 - 4D}}{2}$$

$$T = \lambda_1 + \lambda_2, \quad D = \lambda_1 \lambda_2$$

- The Trace - Determinant Plane



- real distinct eigenvalues:  $T^2 - 4D > 0$  (below the parabola)
  1.  $D < 0 : \lambda_1 < 0 < \lambda_2$  saddle
  2.  $D > 0$  and  $T > 0 : 0 < \lambda_1 < \lambda_2$  source
  3.  $D > 0$  and  $T < 0 : \lambda_1 < \lambda_2 < 0$  sink
- repeated eigenvalues:  $T^2 - 4D = 0$ 
  1.  $T < 0 : \lambda_1 < 0$  sink
  2.  $T > 0 : \lambda_1 > 0$  source
- complex eigenvalues:  $T^2 - 4D < 0$  (above the parabola)
  1. spiral sink:  $T < 0$  (left half of the plane)
  2. spiral source:  $T > 0$  (right half of the plane)
  3. Center:  $T = 0$  ( $D$  - axis)
- The above Trace - Determinant diagram can also be used as a bifurcation diagram.
- Conjugacy of two systems
  - Two linear system  $X' = AX$  and  $Y' = BY$
  - $\phi^A(t, X_0)$  is the flow of  $X' = AX$ , i.e.,  $X(t) = \phi^A(t, X_0)$  is the solution with initial data  $X(0) = X_0$
  - $\phi^B(t, Y_0)$  is the flow of  $Y' = BY$
  - $h : R^2 \rightarrow R^2$  is a homeomorphism (1-1, onto,  $h$  and  $h^{-1}$  are continuous)
  - Definition: These two system is called conjugate if
 
$$\phi^B(t, h(X_0)) = h(\phi^A(t, X_0))$$
  - i.e., if  $X(t)$  is a solution of  $X' = AX$ , then  $h(X(t))$  is a solution of  $Y' = BY$ .
  - $h$  is called a conjugacy.  $h$  maps a solution for  $A$  to a solution for  $B$ .
- Example 1: For linear transformation  $T$ , it is also a conjugacy that maps a solution of  $X' = AX$  to a solution of  $Y' = (T^{-1}AT)Y$

- Example 2: Consider

$$x' = \lambda_1 x \quad \text{and} \quad y' = \lambda_2 y$$

- their flows are, respectively,

$$\phi^i(t, x_0) = x_0 e^{\lambda_i t}, \quad i = 1, 2$$

- if both  $\lambda_1$  and  $\lambda_2$  have the same sign, then they are conjugate with the conjugacy

$$h(x) = \begin{cases} x^{\lambda_2/\lambda_1} & \text{if } x \geq 0 \\ -|x|^{\lambda_2/\lambda_1} & \text{if } x < 0 \end{cases}$$

- verify: for  $x_0 > 0$ ,

$$\begin{aligned} h(\phi^1(t, x_0)) &= h(x_0 e^{\lambda_1 t}) = (x_0 e^{\lambda_1 t})^{\lambda_2/\lambda_1} \\ &= (x_0)^{\lambda_2/\lambda_1} e^{\lambda_2 t} = \phi^2\left(t, (x_0)^{\lambda_2/\lambda_1}\right) = \phi^2(t, h(x_0)) \end{aligned}$$

- Definition: A matrix is called hyperbolic if none of its eigenvalues has real part 0.
- Theorem: Two hyperbolic linear system  $X' = A_i X$  are conjugate iff they have the same number of eigenvalues with negative real part, i.e.,
  - Both have one positive and one negative eigenvalue
  - Both have complex eigenvalues with positive real part (including both eigenvalues are real)
  - Both have complex eigenvalues with negative real part (including both eigenvalues are real)
- The proof in the case of real eigenvalues is similar to Example 2 for canonical forms.
- From this Theorem, all systems of sink (source) or spiral sink (spiral source) are conjugate with each other.
- Homework for Chapter 4: 1, 3, 4, 5a